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# Indicatrix Given by a Square Change of $(\alpha, \beta)$ -metric

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Abstract: Characteristic properties of indicatrix has been studied by so many authors in different situations. In 1984, C. Shibata introduced the concept of  $\beta$ -change in Finsler geometry. Using the theory of  $\beta$ -change, we study the behavior of indicatrix given by square change of famous Z. Shen's square metric.

Keywords— Indicatrix,  $\beta$ -change, Square change, conformal change, Square metric.

## I. INTRODUCTION

Starting from its emergence, the theory of Finsler space [13] is an important topic of research in Differential geometry. C. Shibata [16] introduced the concept of  $\beta$ -change in Finsler geometry. Later on, S.H. Abed [1] generalized the theory of  $\beta$ -change and introduced the concept of conformal  $\beta$ -change in Finsler geometry. The theory of indicatrix has been studied by so many authors [8, 11, 14]. In this paper, we study the behavior of indicatrix under square change of ( $\alpha$ ,  $\beta$ )-metric.

The paper is organized as follows: In section 2, we discuss the theory of  $\beta$ - change in particular square change. In section 3, we consider the indicatrices given by a particular  $\beta$ -change, known a square change and study its properties in detail.

## **II. PRELIMINARIES**

Let M be a connected n-dimensional smooth manifold and let  $TM = \bigcup_{x \in M} T_x M$  be its tangent bundle, where  $T_x M$  is the tangent space at  $x \in M$ . A generic point u in TM is denoted by  $u = (x, y) \in TM$ , where  $y \in T_x M$ . Locally, if  $x = (x^i)$  is a local coordinate system on M, then u =

$$\phi(s) - s\phi'(s) + (b^2 - s^2)\phi''(s) > 0, \qquad (2.1)$$
$$|s| \le b < b_0$$

 $\begin{aligned} \phi(s) - s\phi'(s) &> 0, |s| < b_0 \end{aligned} \tag{2.2} \\ (x, y) &= (x^i, y^i) \in TM \text{, where } i=1, 2...n, \text{ and } y = y^i \frac{\partial}{\partial x^i_x}. \end{aligned}$ 

Recall, that a Finsler metric on *M* is a function *F*:  $TM \rightarrow [0, \infty)$  with properties:

- (i) F is  $C^{\infty}$  on  $\widetilde{TM} := TM \setminus \{0\}$
- (ii)  $F(x, \lambda y) = \lambda F(x, y)$  for any  $\lambda > 0$
- (iii) The hessian matrix  $g_{ij} = \frac{1}{2} \frac{\partial^2 F^2}{\partial y^i \partial y^j}$  is positive definite for all  $(x, y) \in \widetilde{TM}$ .

One of the most studied examples of Finsler metrics are the  $(\alpha, \beta)$ -metrics, i.e., the metrics of the form  $F = F(\alpha, \beta)$  where *F* is a positive 1-homogeneous function of two arguments  $\alpha$  and  $\beta$ .

Here  $\alpha = \sqrt{a_{ij}(x)y^i y^j}$  is a Riemannian metric and  $\beta = b_i(x)y^i$  a 1-form on M. These metrics have a lot of applications [2, 3, 6]. Following Shen, Finsler metric F can be written in the form  $F = \alpha \phi \frac{\beta}{\alpha}$ , where  $\phi: I = [-b, b] \rightarrow [0, \infty]$  is a  $C^{\infty}$ -function, and the interval I can be chosen big enough such that  $r \ge \frac{\beta}{\alpha}$ ,  $\forall x \in M$  and  $y \in T_x M$ .

**Lemma 2.1** (Shen's Lemma) The function  $F = \alpha \phi(s)$ ,  $s = \frac{\beta}{\alpha}$ , is a Finsler metric for any  $\alpha = \sqrt{a_{ij}(x)y^i y^j}$  and any  $\beta = b_i(x)y^i$  with  $\|\beta_x\|_{\alpha} < b_0$  if and only if  $\phi(s)$  is a positive  $C^{\infty}$  function on  $(-b_0, b_0)$  satisfying the following conditions:

Classical examples of  $(\alpha, \beta)$ -metrics are: the Randers metric, namely  $F = \alpha + \beta$ , Matsumoto metric, i.e.,  $F = \frac{\alpha^2}{\alpha - \beta}$ , Z. Shen's square metric, i.e.,  $F = \frac{(\alpha + \beta)^2}{\alpha}$  and many others [9,12].

In particular, we are interested in square metric  $F = \frac{(\alpha + \beta)^2}{\alpha}$ . In this case, we have  $F = \alpha \phi(s)$ , where  $\phi(s) = (1 + s)^2$ . Next, we discuss some definitions and results required for the next section.

**Definition 2.1** If there exist a covariant vector field  $P_i$  such that the hv-curvature tensor  $P_{hijk}$  of  $F^n$  can be written in the form

$$P_{hijk} = P_h C_{ijk} - P_i C_{hjk},$$

then the Finsler space  $F^n$  (n > 2) is called P2- like.

For a *P2*-like Finsler space  $F^n$  (n > 2), we recall [10] the following theorem:

**Theorem 2.1** If  $F^n$  (n > 2) is a P2-like Finsler space, then its hv-curvature  $P_{hijk}$  or v-curvature tensor  $S_{hijk}$ vanishes, i.e.  $S_{hijk} = 0$ .

**Definition 2.2** If the third curvature tensor  $R_{hijk}$  of Cartan space can be expressed in the form

$$R_{hijk} = g_{hj}F_{ik} + g_{ik}F_{hj} - g_{hk}F_{ij} - g_{ij}F_{hk} ,$$

where

$$F_{ik} = \frac{1}{n-2} \left( R_{ik} - \frac{r}{2} g_{ik} \right), R_{hj} = R_{hjm}^m, r = \frac{1}{n-1} R_m^m \text{ then the}$$
  
Finsler space  $F^n$  ( $n > 3$ ) is called R3-like.

For the (v)hv-torsion tensor  $P_{hijk}$  and the (h)hv torsion tensor  $C_{hij}$  we define  $*P_{hij} = P_{hij} - \lambda C_{hij}$ .

where the scalar  $\lambda$  is homogeneous of degree one in  $y^i$  and is given by  $\frac{P_i C^i}{C_i c^i}$  for  $C_j \neq 0$ .

**Definition 2.3** If the torsion tensor  $*P_{hij}=0$ , then the Finsler space  $F^n$  (n > 2) is called a \*P-Finsler space.

**Definition 2.4** [4] If the (v)hv-torsion tensor  $P_{hij} = 0$ , the the Finsler space  $F^n$  is called a Landsberg space.

**Definition 2.5** [6] If the v-curvature tensor  $S_{hijk}$  of a non-Riemannian Finsler space  $F^n$  (n > 4) can be written in the form

 $F^{2}S_{hijk} = h_{hj}M_{ik} + h_{ik}M_{hj} + h_{hk}M_{ij} - h_{ij}M_{hk},$ 

where  $M_{ij}$  is symmetric and indicatory tensor given by  $M_{ij} = \frac{1}{n-3} [S_{ij} - \frac{Sh_{ij}}{2(n-2)}]$ , then it is called S4- like.

Next, we recall the following theorems [17] for later use.

**Theorem 2.2** Every R3-like (non-Landsberg) \*P-Finsler space  $F^n$  (n > 4) is S4- like.

**Theorem 2.3** An R3-like Landsberg space  $F^n$  (n > 3) is a Finsler space satisfying  $S_{hijk} = 0$  or a Riemannian space of constant curvature.

#### **III. INDICATRICES GIVEN BY A SQUARE CHANGE**

Let M be an n-dimensional connected, smooth manifold equipped with a Finsler metric F. Then for any  $x \in M$ , the tangent space  $T_x M$  can be regarded as an n-dimensional Riemannian space with the fundamental metric tensor  $g_{ij}(x, y)$ , where  $x = (x^i)$  is fixed. Then in terms of Cartan connection  $C\Gamma$  of the Finsler space  $F^n$  the components  $C_{jk}^i$  of (h)hv-torsion tensor are Christoffel symbols of  $T_x M$  and the *v*-curvature tensor  $S_{hjk}^i$  is the Riemannian curvature tensor of  $T_x M$ . The indicatrix  $I_x$  at a point x is a hypersurface of the Riemannian space  $T_x M$ , defined by the equation F(x, y) = 1, where x is fixed. Consequently,  $I_x$  is regarded as an (n-1)dimensional Riemannian space.

Next, we consider the Z. Shen's square metric  $F = \frac{(\alpha + \beta)^2}{F}$ , and apply  $\beta$ -change on it.

Let us denote the new metric by  $\overline{F}$ , then

$$\bar{F} = \frac{(F+\beta)^2}{F} = \mathbf{f}(F,\beta) \tag{3.1}$$

is called square change of  $(\alpha, \beta)$ -metric, where  $\beta = b_i(x)y^i$  is a non-zero 1-form on M.

Differentiating (3.1) with respect to F and  $\beta$  up to and including second order, we get the following relations:

$$f_1 = \frac{\partial \bar{F}}{\partial F} = \frac{F^2 - \beta^2}{F^2}, f_2 = \frac{\partial \bar{F}}{\partial \beta} = \frac{2(F + \beta)}{F}, f_{11} = \frac{\partial^2 \bar{F}}{\partial F^2} = \frac{2\beta^2}{F^3}, \quad f_{22} = \frac{\partial^2 \bar{F}}{\partial \beta^2} = \frac{2}{F}, f_{12} = \frac{\partial^2 \bar{F}}{\partial F \partial \beta} = \frac{-2\beta}{F^2}$$
(3.2)

Since  $\overline{F} = f(F,\beta)$  is positively homogeneous of of degree one, therefore using Euler's theorem on homogeneous functions we have 
$$\begin{split} Ff_1 + f_2\beta &= f = \bar{F}, \ Ff_{12} + \beta f_{22} = 0, \ Ff_{11} + \beta f_{12} = 0 \\ (3.3) \\ \text{For the later use, let us define p, q and } q_0 \text{ as follows:} \\ p &= \frac{ff_1}{F} = \frac{(F+\beta)^3(F-\beta)}{F^4}, q = ff_2 = \frac{2(F+\beta)^3}{F^2}q_0 = ff_{22} = \frac{2(F+\beta)^2}{F^2} \\ (3.4) \\ \text{Furthermore, } \bar{l}_i &= \bar{F}_{y^i} \text{ gives} \\ \bar{l}_i &= f_1 l_i + f_2 b_i \\ \text{Differentiating (3.5) with respect to } y^j, \text{ we get the angular metric tensor } \bar{h}_{ij} &= \bar{F} \dot{\partial}_i \dot{\partial}_j \bar{F} \text{ of } \bar{F}^n \end{split}$$

$$\bar{h}_{ij} = ph_{ij} + q_0 m_i m_j \tag{3.6}$$

where the covariant vector  $m_i$  is defined by

$$m_i = b_i - \frac{\beta y_i}{F^2}. \tag{3.7}$$

Here it is to be noted that  $m_i$  is a non-zero vector orthogonal to  $y^i$ . For, if  $m_i = 0$ , then  $F^2 b_i - \beta y_i = 0$ . Differentiation of this with respect to  $y^j$  gives  $\beta g_{ij} - 2Fl_j b_i + b_j y_{i=0}$ , which leads to a contradiction  $g_{ij} - l_i l_j = 0$ .

Now, from (3.3), (3.4), (3.5), (3.6) and (3.7) the fundamental metric tensor  $\bar{g}_{ij} = \frac{1}{2} \dot{\partial}_i \dot{\partial}_j \bar{F}^2 = \bar{h}_{ij} + \bar{l}_i \bar{l}_j$  of  $\bar{F}^n$  is given by

$$\bar{g}_{ij} = pg_{ij} + p_0b_ib_j + p_{-1}(b_iy_j + b_jy_i)$$

 $+p_{-2}y_iy_j$ (3.8)

where we put

$$p_0 = q_0 + f_2^2 = \frac{6(F+\beta)^2}{F^2} q_{-1} = \frac{f_{12}}{F} = \frac{-2\beta(F+\beta)^2}{F^4},$$

$$p_{-1} = q_{-1} + \frac{pf^2}{f} = \frac{2(F^3 - 3F\beta^2 - 2\beta^3)}{F^4}$$

$$q_{-2} = \frac{f(f_{11} - \frac{f_1}{F})}{F^2} = \frac{(F+\beta)^2(F^2 + 3\beta^2)}{F^6}, p_{-2} = q_{-2} + \frac{p^2}{f^2}$$
$$= \frac{2(F+\beta)^2(F^2 - F\beta + 2\beta)^2}{F^6}$$

Next we have theorem:

**Theorem 3.1** If a Finsler space  $F^n$  (n > 4) is a S4-like, then the Finsler space  $\overline{F}^n$  obtained by square change is also S4-like.

A tensor which is invariant under the square change, we call it S-invariant tensor.

The v-curvature S<sup>\*</sup><sub>hiik</sub> under square change, is given by

$$FS_{hijk}^{*} = S_{hijk} + \frac{1}{n-3} U_{jk} [h_{ij}S_{hk} + h_{nk}S_{ij} - Sh_{ij}h_{hk}]$$
(3.9)

where  $U_{jk}$  denotes the interchange of indices j, k and subtraction.

Assume that  $S_{hijk}^* = S_{hijk}$ , then we say that  $S_{hijk}^*$  is S-variant.

For a S4-like Finsler space, let us recall the following theorem [6].

**Theorem 3.2** Let  $F^n$  (n > 4) be a S4-like Finsler space. Then the indicatrix  $I_x$  is conformally flat.

If the v-curvature tensor  $S^*_{hijk}$  is S-invariant under square change, then we have the following theorem:

**Theorem 3.3** A non-Riemannian Finsler Space  $F^n$  (n > 4) is S4-like if and only if the S-invariant tensor  $S^*_{hijk}$  vanishes. By theorem (2.1), equation (3.9), theorem (3.3), theorem (3.1) and theorem (3.2), we find the following.

**Theorem 3.4** If  $F^n$  (n > 4) is P2-like Finsler space, then the indicatrix  $\bar{I}_x$  of  $\bar{F}^n$  obtained from  $F^n$  by square change is conformally flat if  $P_{hijk} \neq 0$ .

From theorem 2.2, theorem 3.1, and theorem 3.2, we find the following:

**Theorem 3.5** If  $F^n$  (n > 4) is R3-like (non-Landsberg) \*P-Finsler space, then the indicatrix  $\bar{I}_x$  of  $\bar{F}^n$  obtained from  $F^n$  by a square change is conformally flat.

From the theorem (2.3), equation (3.9), theorem (3.3), theorem (3.1) and theorem (3.2), we immediately find:

**Theorem 3.6** Assume that  $F^n$  (n > 4) is R3-like Landsberg space. Then the indicatrix  $\overline{I}_x$  of  $\overline{F}^n$ , obtained from  $F^n$  by a square change is conformally flat, provided  $F^n$  is not a Riemannian space of constant curvature.

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